



5-year warranty



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Power consumption in operation	1 W
	Power consumption in rest position	0.2 W
	Transformer sizing	1.5 VA (class 2 power source)
	Electrical Connection	Screw terminal (for 26 to 14 GA wire)
	Overload Protection	electronic throughout full rotation
Functional data	Torque motor	18 in-lb [2 Nm]
	Direction of motion motor	by electrical installation
	Manual override	disengage with magnet
	Angle of rotation	0...287.5°, Without limitation: endless With one end stop clip Z-ESCM: 315°
	Angle of rotation note	Without limitation: endless With one end stop clip Z-ESCM: 315°
	Running Time (Motor)	35 s, constant, independent of load
	Running time motor note	constant, independent of load
	Noise level, motor	45 dB(A)
	Shaft Diameter	1/4...1/2" round, centers on 3/8"
	Position indication	Mechanically, pluggable (with integrated magnet for gear disengagement)
Safety data	Degree of protection IEC/EN	IP20
	Degree of protection NEMA/UL	NEMA 1 UL Enclosure Type 1
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU; Listed to UL 2043 - suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC
	Quality Standard	ISO 9001
	Ambient temperature	-22...122°F [-30...50°C]
	Storage temperature	-40...176°F [-40...80°C]
	Ambient humidity	max. 95% r.H., non-condensing
	Servicing	maintenance-free
	Weight	Weight
		0.46 lb [0.21 kg]
Materials	Housing material	UL94-5VA

Product features

Application Damper actuator for operating air control dampers in ventilation and air-conditioning systems for building services installations.

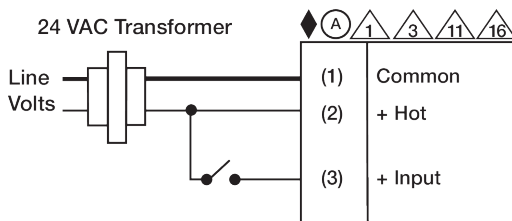
- For air control dampers up to approximately 4.5 sq ft
- Torque 2 Nm
- Nominal voltage AC/DC 24 V
- Control: Open-close or 3-point
- Running time 35 sec. @ 90°

Operation Simple direct mounting on the damper spindle with a universal spindle clamp or form fit, supplied with an anti-rotation bracket to prevent the actuator from rotating. Manual operation is possible with a magnet (the gear latch remains disengaged as long as the magnet is in place). Adjustable angle of rotation with mechanical end stops, that requires no tools to move or remove. The actuator is overload-proof, requires no limit switches and automatically stops when the end stops is reached. The actuator uses a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode. Belimo's Halomo sensorless brushless DC motor spins by reversing the poles of stationary electromagnets housed inside rotational permanent magnets. The electromagnetic poles are switched by the an ASIC developed by Belimo. Unlike the conventional DC motor, there are no brushes to wear or commutators to foul. This means the brushless DC motor adds accuracy and reduces power consumption in a holding mode.

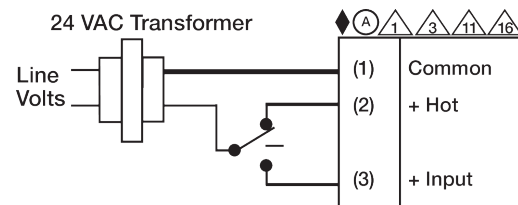
Typical specification Floating point, on/off control damper actuators shall be electronic direct coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft from 1/4" to 1/2". Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have manual override on the cover. If required, actuators will be provided with screw terminal strip for electrical connections (CMB24-3-T). Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Electrical installation

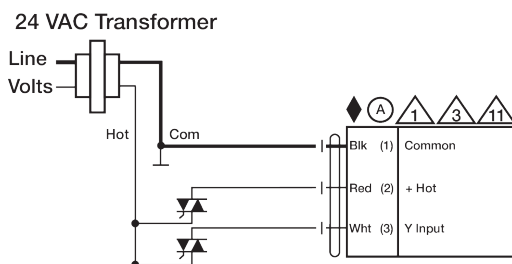
- Ⓐ Actuators with appliance cables are numbered.
- 1 Provide overload protection and disconnect as required.
- 3 Actuators may also be powered by 24 VDC.
- 6 Actuators Hot wire must be connected to the control board common. Only connect common to neg. (-) leg of control circuits. Terminal models (-T) have no-feedback.
- 11 Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.
- 16 Actuators are provided with a numbered screw terminal strip instead of a cable.



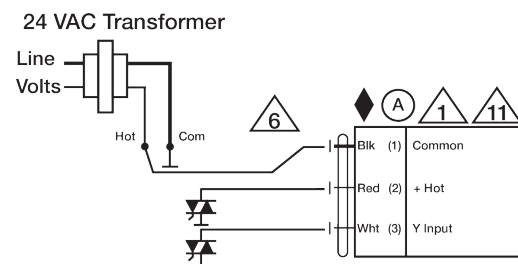
On/Off



Floating Point



Floating Point - Triac Source



Floating Point - Triac Sink

Dimensions

Dimensional drawings

